#### **Features**

- 8-bit 80C52-compatible Microcontroller
  - Fully instruction set compatible
  - Pin-to-pin package compatible
- Power voltage range: V<sub>CC</sub>= 2.4V ~ 3.6V
- Optional 12 clocks or 6 clocks per machine cycles operation
- Operating speed: Up to 45MHz for both 12 clocks and 6 clocks per machine cycle
- · Memory architecture
  - 512 bytes on-chip RAM
  - 64K bytes on-chip flash memory
  - 64K bytes program and data memory address spaces
  - Provides In-system programming (ISP) to update the program code
- Four 8-bit bi-directional I/O Ports (P0, P1, P2, P3) and P4.0~P4.3, and except P1 is not 5V-tolerant, P0/2/3/4 all are 5V-tolerant
- Three 16-bit programmable timer/counters, Timer2 is an up/down counter with programmable clock output on P1.0
- One watchdog timer
- One enhanced UART, provides frame-error detection and hardware address- recognition
- Power saving mode
  - Idle and Power-down modes
  - Waking up the power-down mode by P3.2 and P3.3
- Dual DPTR for fast-moving external data memory
- 6-source and 4-level interrupt structure
- Inhibit ALE-signal output for the low EMI
- 3-level code protection
- · Packages:
  - PDIP 40: MPC89L516X2PLCC 44: MPC89L516X2P
  - PQFP 44: MPC89L516X2F

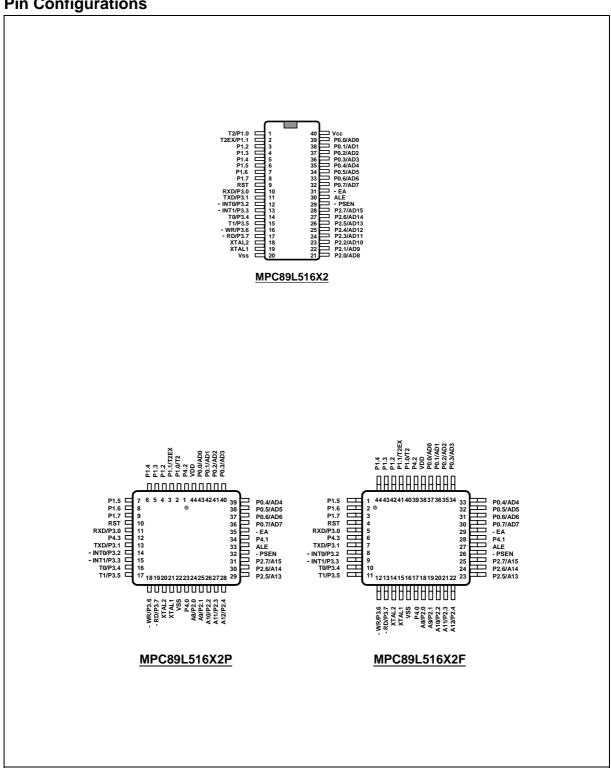
### **General Description**

MPC89L516X2 is a powerful 8-bit 80C52-compatible Microcontroller with advanced embedded flash memory technology. It contains a 64kx8 Flash memory, a 512x8 RAM, a watch-dog timer, a full duplex UART, 3 timer/counters and dual DPTR. In additional, MPC89L516X2 is designed with an new accelerative architecture, its speed can executes twice faster than a conventional 80C52 series, and the users can easily change the 12 clocks to 6 clocks per machine cycle operation on the programmer.

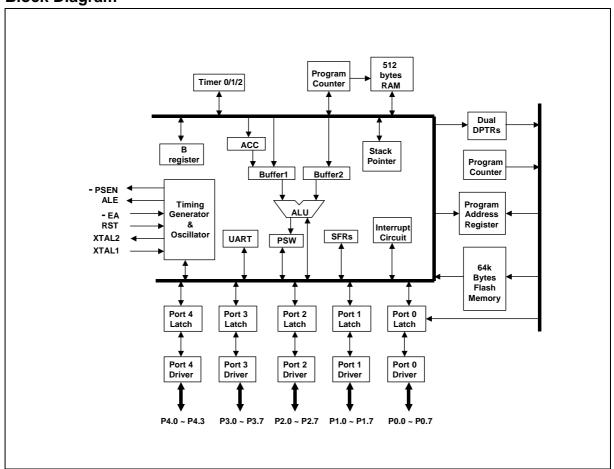
## **Pin Description**

PIN Name	I/O	Description
P0.0 ~ P0.7	I/O	Port 0 is bi-directional I/O port with an open-drain. Port 0 is also the multiplexed low-order address and data bus during accesses to the external program and data memory.
P1.0 ~ P1.7	I/O	Port 1 is a general purpose I/O (GPIO) port with the internal pull-ups and also provides the alternate functions for the timer 2.
P2.0 ~ P2.7	I/O	Port 2 is an 8-bit bi-directional I/O port with internal pull-ups. Except acting as GPIO, Port 2 outputs the high-order address byte during accessing the external data and program memory.
P3.0 ~ P3.7	I/O	Port 3 is a GPIO with internal pull-ups and also serves the special functions of the conventional 80C52 series, as listed below:  RXD/P3.0: Serial input  TXD/P3.1: Serial output  INT0 /P3.2: External interrupt 0  INT1/P3.3: External interrupt 1  T0/P3.4: Timer 0 external Input  T1/P3.5: Timer 1 external Input  WR /P3.6: External data memory write strobe  RD /P3.7: External data memory read strobe
P4.0 ~ P4.3	I/O	Port 4 is an extended I/O port such like Port 1, but it can be available only on 44-PLCC and 44-PQFP.
RST		A high level on this pin for at least two machine cycles to reset this device.
XTAL1		Input to the oscillator amplifier.
XTAL2	0	Output from the oscillator amplifier, and also is the inversion of XTAL1.
ĒĀ	I	EA (External Access) has to be externally held low to enable the device to fetch code from the external program memory.
PSEN	0	PSEN (Program Strobe Enable) is low active, when the read strobe to the external program memory.
Vss	I	Ground input.
Vdd	ı	Power supply input.

# **Pin Configurations**



# **Block Diagram**



# **Special Function Registers**

SYMBOL	DESCRIPTION	ADDRESS			BIT ADD	RESS A	ND SYN	1BOL			INITAL
STWIBUL	DESCRIPTION	ADDRESS	MSB							LSB	VALUE
+ P0	Port 0	80H	87H	86H	85H	84H	83H	82H	81H	80H	11111111B
CD	Ctack Dainter	0411	AD7	AD6	AD5	AD4	AD3	AD2	AD1	AD0	
SP DPL	Stack Pointer Data Pointer Low	81H 82H									00000111B 00000000B
DPH	Data Pointer High	83H									00000000B
PCON	Power Control	87H	SMOD	_	-	POF	GF1	GF0	PD	IDL	00XX0000B
			9FH	9EH	9DH	9CH	9BH	9AH	89H	88H	
+ TCON	Timer Control	88H	TF1	TR1	TF0	TR0	IE1	IT1	IE0	IT0	00000000B
TMOD	Timer Mode	89H	GATE	C/-T	M1	M0	GATE	C/-T	M1	M0	00000000B
TL0	Timer Low 0	8AH									0000000B
TL1	Timer Low 1	8BH									00000000B
TH0	Timer High 0	8CH									00000000B
TH1	Timer High 1	8DH		ı		ı	1	ı	1	1 40	00000000B
AUXR	Auxiliary	8EH	- 0711	-	-	- 0411	-	-	-	AO	XXXXXXX0B
+ P1	Port 1	90H	97H -	96H -	95H -	94H -	93H -	92H -	91H T2EX		11111111B
+ SCON	Serial Control	98H	<b>9FH</b> SM0/FE	9EH SM1	9DH SM2	9CH REN	9BH TB8	9AH RB8	<b>99H</b>	<b>98H</b> RI	00000000B
SBUF	Serial Data Buffer	99H	OWO/I L	OWIT	OIVIZ	IXEIX	100	TABO		131	XXXXXXXXB
			A7H	A6H	A5H	A4H	A3H	A2H	A1H	A0H	
+ P2	Port 2	A0H	A15	A14	A13	A12	A11	A10	A9	A8	11111111B
AUXR1	Auxiliary 1	A2H	•	-	-	-	-	-	-	DPS	XXXXXXX0B
+ IE	Interrupt Enable	A8H	<b>AFH</b> EA	AEH -	ADH ET2	ACH ES	ABH ET1	AAH EX1	A9H ET0	A8H EX0	0000000B
SADDR	Slave Address	A9H		l.		l.		l.			00000000B
+ P3	Port 3	В0Н	<b>B7H</b> -RD	B6H -WR	<b>B5H</b> T1	<b>B4H</b> T0	B3H -INT1	<b>B2H</b> -INT0	B1H TXD	B0H RXD	11111111B
IPH	Interrupt Priority High	B7H	-	-	PT2H	PSH	PT1H	PX1H	PT0H		X0000000B
+ IP	Interrupt Priority	B8H	BFH	BEH -	BDH PT2	BCH PS	BBH PT1	BAH PX1	<b>B9H</b> PT0	B8H PX0	X0000000B
SADEN	Slave Address Mask	В9Н			1 12	10		1 7 1	1110	170	00000000B
			C7H	C6H	C5H	C4H	СЗН	C2H	C1H	C0H	
+ P4	Port 4	C0H	-	-	-	-	P4.3	P4.2	P4.1	P4.0	XXXXXX11B
+ T2CON	Timer 2 Control	C8H	CFH	CEH	CDH	CCH	CBH	CAH	C9H	C8H	0000000B
T2MOD	Timer2 Mode Control	C9H	TF2	EXF2	RCLK -	TCLK -	EXEN2	TR2	T20E	CP/-RL DCEN	XXXXXXX00B
RCAP2L	Timer2 Capture Low	CAH		_		_		_	IIZOL	DOLIN	00000000B
RCAP2H	Timer2 Capture Low	CBH									00000000B
TL2	Timer Low 2	CCH									00000000B
TH2	Timer High 2										00000000B
	riinei riigirz	CDH	D7H	D6H	D5H	D4H	D3H	D2H	D1H	D0H	
+ PSW	Program Status Word	D0H	CY	AC	F0	RS1	RS0	OV	-	P	000000X0B
	Accumulator	E0H	E7H	E6H	E5H	E4H	E3H	E2H	E1H	E0H	0000000B
WDTCR	Watch-dog Timer	E1H	-	-	WDEN	WDCL	WDIDL	PS2	PS1	PS0	XX000000B
IFD	ISP Flash Data	E2H									0000000B
IFADRH	ISP High Flash Address	E3H									0000000B
IFADRL	ISP Low Flash Address	E4H									00000000B
IFMT	ISP Mode Table	E5H	-	-	-	-			<u> </u>		XXXX0000B
SCMD	ISP Sequential Command Data	E6H									XXXXXXXXB
ISPCR	ISP Control Register	E7H	ISPEN	BS	SRST	-	-	ICK2	ICK1	ICK0	000XX000B
<b>+</b> B	B Register	F0H	F7H	F6H	F5H	F4H	F3H	F2H	F1H	F0H	00000000B

### Notes:

1.The SFRs that are marked with a plus sign (+) are both byte-addressable and bit-addressable.

### **Functional Description**

The MPC89L516X2 architecture consists of an enhanced 80C52 micro-controller, a 64k bytes flash memory, 512 bytes on-chip RAM, three timer/counters, and a serial port. The micro-controller supports fully compatible instruction with standard 80C52, and also can address both a 64K program memory space and a 64K data memory space.

### **Memory Structure**

There are 256 bytes on-chip RAM, 256 bytes on-chip expanded RAM (EX-RAM) and a 64k bytes flash memory available for MPC89L516X2. The internal data memory space is divided into four blocks: the lower 128 bytes RAM, the upper 128 bytes RAM, 128 bytes SFR and 256 bytes expanded RAM.

The four blocks are:

- The lower 128 bytes (00H~7FH) are accessed by direct and indirect addressing
- The upper 128 bytes (80H~FFH) are accessed by indirect addressing only
- The special function registers (SFR: 80H~FFH) are accessed by direct addressing only
- The 256 bytes expanded RAM (EX-RAM: 00H~ FFH) are indirectly accessed by the move external data memory instruction, MOVX @Ri, only

The on-Chip RAM is mapped as the following figure. MPC89L516X2 also provides an expanded 256 bytes of RAM on the chip. These bytes are only accessed by the two instructions, using MOVX A, @Ri for the reading and MOVX @Ri, A for the writing. When these two instructions are executed, there is no influence on P0. This is different from the standard 80C52 which P0 emits the address and is accessed the data in/out. In other words, only MOVX @Ri instruction is fixed to access on-chip 256 bytes EX-RAM, and for MOVX @DPTR instruction, it is used to access the external data memory higher than EX-RAM, and can be addressing up to 64K bytes.

	FFH		
Expanded 256 bytes RAM accessed by MOVX @Ri	7FH	Upper 128 bytes RAM accessed by indirect addressing	128 bytes SFRs accessed by direct addressing
MOVA @RI		Lower 128 bytes RAM accessed by indirect and direct addressing	
	оон		

#### Timer/Counter

MPC89L516X2 has three timer/counters. All of them are the same with the standard 80C52. But Timer2 supports the auto-reload up-down mode, which is a new-added function.

#### 1. Timer0 and Timer1

These Timers can be configured as four modes: 1. Mode0 is 13-bit counter, 2. Mode1 is 16-bit counter, 3. Mode2 is 8-bit counter with automatic reload. 4. Mode3 can separate two 8-bit counters, and these modes are all the same with the standard 80C52.

#### 2. Timer2

Timer2 has four operation modes: Capture mode, Auto-reload up-only mode, Auto-reload up-down mode and Baud-rate generator mode. MPC89L516X2's Timer 2 also provides a programmable clock-out on P1.0.

### **Auto-Reload Up-Only Mode**

In Auto-reload up-only mode of the standard 80C52, Timer2 can be configured to count up with a software-defined value to be reloaded. When reset is applied the DCEN =0 and CP/RL2 =0, Timer2 is at the auto-reload up-only mode. An overflow on Timer2 or 1-to-0 transition on T2EX pin will load RCAP2H and RCAP2L contents onto Timer2, also set TF2 and EXF2, respectively (See Figure 1).

#### **Auto-Reload Up-Down Mode**

Auto-reload up-down mode is a new-added powerful function. Timer2 can be configured to count up or down. When DCEN =1 and CP/RL2 =0, Timer2 is at the auto-reload up-down mode. The counting direction is determined by T2EX pin. If T2EX=0, counting up, otherwise counting down. An overflow on Timer2 will set TF2 and toggle EXF2. EXF2 cannot generate the interrupt request in this mode. If the counting direction is DOWN, the overflow loads #FFFFh onto Timer2. Otherwise, the overflow would load RCAP2H, RCAP2L contents onto Timer2 if the counting direction is UP (See Figure 2).

### **Programmable Clock-Out**

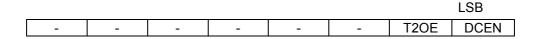
When T2OE bit (in the T2MOD) is set and  $C/\overline{T}$  (in T2CON) bit is cleared, Timer 2 overflow pulse will toggle P1.0 pin latch to generate a 50% duty clock. In this clock-out mode, Timer 2's rollovers will not generate an interrupt. The clock-out frequency is determined by the following equation:

Oscillator frequency / (N x (65536 – RCAP2H, RCAP2L)),

Where: N=2 for 6 clock mode, N=4 for 12 clock mode,

(RCAP2H, RCAP2L)= the content of RCAP2H and RCAP2L stored as a 16-bit integer-unsigned.

### TMOD (Timer Mode Register, Address: 0C9H)



- T2OE: Timer 2 Output Enable. It enables the clock-out function of Timer 2 on P1.0 by setting.
- DCEN: Down Count Enable. It allows Timer 2 to be configured as an up/down counter by setting.

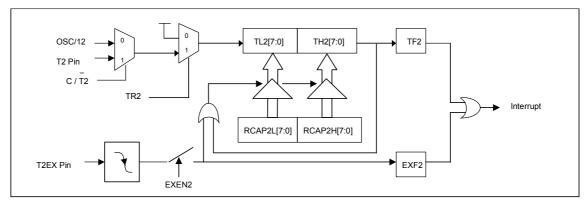


Figure 1: Auto-Reload Up-only Mode

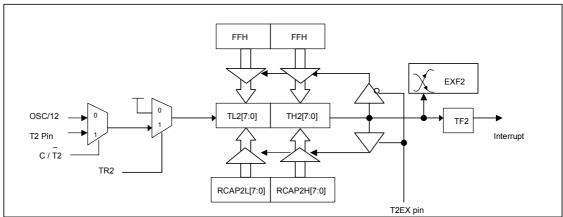


Figure 2: Auto-Reload Up-Down Mode

### **Interrupt Structure**

MPC89L516X2 has a 6-source and 4-level interrupt structures. Each interrupt source can be individually enabled or disabled by setting or clearing a bit in the IE SFR. This register also contains a global disable bit (EA), which can be reset all interrupts to disable at once. Each interrupt source has two corresponding bits to represent its priority. One is located in IPH SFR, and the other is placed in the IP SFR. Higher-priority interrupt request will not be interrupted by lower-priority interrupt request. If both interrupt requests from different priority levels are received simultaneously, the request from the higher priority would be serviced. If both interrupt requests from the same priority levels are received simultaneously, an internal polling sequence determines which request would be serviced. The following interrupt table shows the internal polling sequence in the same priority level and the interrupt vector address.

### **Interrupt Vector And Priority Table**

Source	Vector Address	Priority Level
External interrupt 0	03H	1 (Highest)
Timer 0	0BH	2
External interrupt 1	13H	3
Timer 1	1BH	4
Serial port	23H	5
Timer 2	2BH	6 (Lowest)

## IE (Interrupt Enable Register, Address: 0A8H)

 EA
 \_
 ET2
 ES
 ET1
 EX1
 ET0
 EX0

- EA: Global disables all interrupts when cleared, EA=0.
- ET2: When set, enables Timer 2 interrupt.
- ES: When set, enables the serial port interrupt.
- ET1: When set, enables Timer 1 interrupt.
- EX1: When set, enables external interrupt 1.
- ET0: When set, enables Timer 0 interrupt.
- EX0: When set, enables external interrupt 0.

## IP (Interrupt Priority Register, Address: 0B8H)

LSB - PT2 PS PT1 PX1 PT0 PX0

- PT2: PT2=1 sets the Timer 2 to high priority level.
- PS: PS=1 sets the serial port to high priority level.
- PT1: PT1=1 sets the Timer 1 to high priority level.
- PX1: PX1=1 sets the external interrupt 1 to high priority level.
- PT0: PT0=1 sets the Timer 0 to high priority level.
- PX0: PX0=1 sets the external interrupt 0 to high priority level.

## IPH (Interrupt Priority High Register, Address: 0B7H)

							LOD	
-	-	PT2H	PSH	PT1H	PX1H	PT0H	PX0H	ì

- PT2H: PT2H=1 sets the Timer 2 to higher priority level.
- PSH: PSH=1 sets the serial port to higher priority level.
- PT1H: PT1H=1 sets the Timer 1 to higher priority level.
- PX1H: PX1H=1 sets the external interrupt 1 to higher priority level.
- PT0H: PT0H=1 sets the Timer 0 to higher priority level.
- PX0H: PX0H=1 sets the external interrupt 0 to higher priority level.

There are three SFRs (IE, IP and IPH) to form the 4-level priority interrupt. The priority of each interrupt is determined as the following table:

#### **Interrupt Priority Level Table**

IPH	IP	Interrupt Priority Level
1	1	Level 3(Highest)
1	0	Level 2
0	1	Level 1
0	0	Level 0 (Lowest)

#### I/O Ports

MPC89L516X2's port structure has the same I/O ports as the standard 80C52, and an expanded bit- addressable port 4. The address of the port 4 is 0C0H. The port 4 has only 4 pins (P4.0  $\sim$  P4.3), and is also available on 44-pin PLCC and 44-pin PQFP. Therefore, only four bits (P4<3:0>) in the P4 SFR can be used.

### WatchDog Timer (WDT)

The Watchdog timer (WDT) is organized as a 15-bit free-running counter that will generate the reset to MPC89L516X2 if the WDT overflow. The WDT is very useful for the system that may be sensitive by the power glitches. The power noise and the disturbances of the electro-magnetic devices will cause the abnormal operation. By clearing this WDT periodically, the user can easily recover this uncertain error. MPC89L516X2 has a programmable pre-scale (PS0~PS2) to as the time base source of the WDT. To enable the WDT by setting the WDEN bit in the WDTCR SFR, then the 15-bit free-running counter starts to count with the pre-scale value. It will generate the reset signal when the overflow occurs. Generally, the user must clear the 15-bit free-running counter and the pre-scale by writing 1 to the WDCL bit in the WDTCR SFR before WDT's overflow occurs.

The WDT period is determined by the following equation:

(N x Pre-scale x 2<sup>15</sup>) / Oscillator frequency, where: N=12 for 12 clock mode, N=6 for 6 clock mode.

### WDTCR (Watchdog Timer Control Register, Address: 0E1H, Write-Only)

							LSB
-	-	WDEN	WDCL	WDIDL	PS2	PS1	PS0

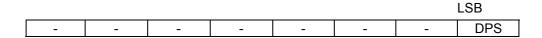
- WDEN: WDT enable bit. When set, WDT is started.
- WDCL: WDT clear bit. When set, WDT will recount. Hardware will automatically clear this bit.
- WDIDL: When set, WDT is enabled in the idle mode. When clear, WDT is disabled in the idle mode.
- PS0~PS2: Pre-scale value of Watchdog timer is shown as the bellowed table:

PS2	PS1	PS0	Pre-scale	WDT period @20MHz and 12 clocks mode
0	0	0	2	39.3 mS
0	0	1	4	78.6 mS
0	1	0	8	157.3 mS
0	1	1	16	314.6 mS
1	0	0	32	629.1 mS
1	0	1	64	1.25 S
1	1	0	128	2.5 S
1	1	1	256	5 S

### **Dual DPTR**

There are two 16-bit DPTR registers that address the external memory. A DPS bit in the AUXR1 SRF is used to switch between DPTR0 and DPTR1.

## **AUXR1 (Auxiliary Register 1, Address: 0A2H)**



 When DPS=0, MPC89L516X2 selects DPTR0, and when DPS=1, then MPC89L516X2 selects DPTR1.

### Reset

The RESET pin, which is the input to the schmitt trigger, is the input for chip reset. The level change of RST-pin has to keep at least two-machine cycle.

### Power-Saving and EMI-Reduced Modes

MPC89L516X2 has two power-saving modes: idle mode and power-down mode. The following table shows the status of I/O ports during the idle and power-down modes. MPC89L516X2 also provides the EMI-reduced mode.

Mode	Program Memory	ALE	PSEN	Port 0	Port 1	Port 2	Port 3
Idle	Internal	1	1	Data	Data	Data	Data
Idle	External	1	1	Float	Data	Address	Data
Power-Down	Internal	0	0	Data	Data	Data	Data
Power-Down	External	0	0	Float	Data	Data	Data

#### Idle Mode

When the IDL bit in the PCON SFR is set, MPC89L516X2 enters the idle mode. In this mode, the internal clock is frozen the micro-controller, but the peripherals, interrupt, timer, watchdog timer and serial port will continue to be worked. There are two ways to exit the idle mode. One way is to enable any interrupt, and the other way is to pull RST-pin to high.

#### **Power-down Mode**

When the PD bit in the PCON SFR is set, MPC89L516X2 enters the power-down mode. In this mode, the on-chip oscillator is stopped, and the contents of on-chip RAM and SFRs are maintained. There are two ways to wake-up MPC89L516X2 from power-down mode, RST-pin and  $\overline{\text{INT0}}$  /  $\overline{\text{INT1}}$  pins. When using RST-pin, there will be carefully to keep RST-pin active for at least 10ms in order for a stable clock.

This power-down mode can be woken-up by either RST-pin or  $\overline{\text{INT0}}$  / $\overline{\text{INT1}}$  pins while  $\overline{\text{INT0}}$  or  $\overline{\text{INT1}}$  external interrupt is enabled. When MPC89L516X2 is woken-up by RST-pin, the program code will execute from the address 0000H, and if it is woken-up by  $\overline{\text{INT0}}$  or  $\overline{\text{INT1}}$  pin, then the program code will run the instruction which follows the instruction making MPC89L516X2 into the power-down mode. The example instructions are as follows:

ORL PCON, #02H; Enable the power-down mode

NOP ; Need to add this "NOP" instruction for waking-up by INT0 or INT1 pin

## **EMI-Reduced Mode**

When set the AO bit in the AUXR SFR (Address: 08EH), MPC89L516X2 will disable the ALE output if no external access is needed.

#### **On-Chip Flash Memory Characteristics**

MPC89L516X2's on-chip flash memory is divided into two blocks, one is the main memory which contains 64k bytes user code. The other is the information memory, which consists two option registers, which are OR0 and OR1. It is used for the security and changing the operating speed.

### **Security And Speed Bits**

MPC89L516X2's information memory has two option registers, OR0 and OR1, to determine the security and the operating speed. They are only used on the programmer. Three-level code protections are implemented in MPC89L516X2 by clearing these bits in the OR0 register. This code-protected operation is only done on the programmer. The first level is the LOCK bit. If the LOCK bit is cleared to 0, the data read-out on the programmer will always be 0FFH. The ENCRYPT bit is the second level protection. Clearing the ENCRYPT bit will encrypt the data while reading out the data on the programmer. The third level protection is MOVCL, clearing the MOVCL bit will disable the MOVC operation when the execution is from the external memory. There is another optional register (OR1) for selecting one operating speed between 12T and 6T, to select in MPC89L516X2 by clearing the EN6T bit in the OR1 register. If 6T is selected, the performance will be increased twice than the conventional 80C52 series. The default speed of MPC89L516X2 is the same as the conventional 80C52 that need 12 clocks for each machine instruction cycle.

## OR0 (Option Register 0, Address: 10000H):

							LOD
ISP_SA3	ISP_SA2	ISP_SA1	ISP_SA0	HWEN_ISP	MOVCL	ENCRYPT	LOCK

Note: It locates at flash memory address, 10000H, and can be only programmed on the programmer.

- MOVCL: MOVC instructions lock bit. When it is selected (clearing to 0), MOVC instructions
  executed from the external program memory will be inhibited the access of the code
  from the internal memory. When this bit is 1, then the MOVC instruction has no any
  limitation
- ENCRYPT: Encryption bit. When it is selected (clearing to 0), the code dumping out from the programmer is encrypted. When this bit is 1, the encryption is disabled.
- LOCK: Lock bit. When it is selected (clearing to 0), the code reading out from the programmer is always 0FFH.
- ISP\_SA0 ~ ISP\_SA3: ISP space adjustment bit. These bits are used for the ISP operation only, and the details please see "In-system programming application note".
- HWEN\_ISP: Hardware enable ISP bit. This bit is also used for the ISP operation only, and the
  details please see "In-system programming application note"

I SR

## OR1 (Option Register 1, Address: 10001H):

							LSB
-	_	-	-	-	EN6T	-	-

LOD

Note: It locates at flash memory address, 10001H, and can be only programmed on the programmer.

EN6T: Enhanced 6T bit. When it is selected (clearing to 0), the speed of MPC89L516X2 will
change to 6 clocks for each machine instruction cycle. When this bit is 1(default value),
the operating speed maintains 12 clocks.

## **Absolute Maximum Ratings**

PARAMETER	RATING	MIN.	MAX.	UNIT
Voltage on any pin except VDD/Vss and P1	Vpin	-0.5	5.5	V
Operating Temperature	ТА	0	+70	$^{\circ}\!\mathbb{C}$
Storage Temperature	Tst	-40	+125	$^{\circ}\!\mathbb{C}$

Note: Exposure to conditions beyond those listed under Absolute Maximum Ratings may adversely affect the life and reliability of the device.

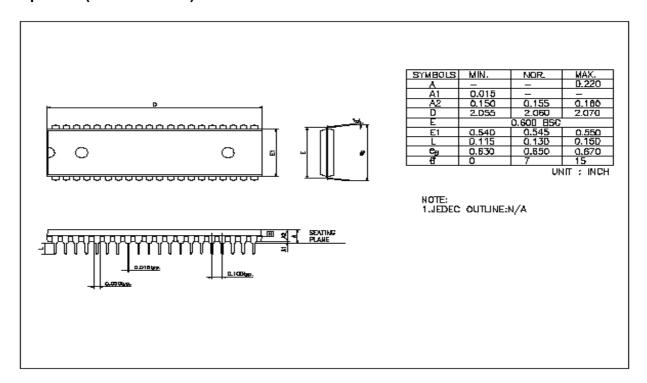
### **DC Characteristics**

VSS = 0V, TA = 25  $^{\circ}\mathrm{C}$  and 12 clocks per machine cycle ,unless otherwise specified

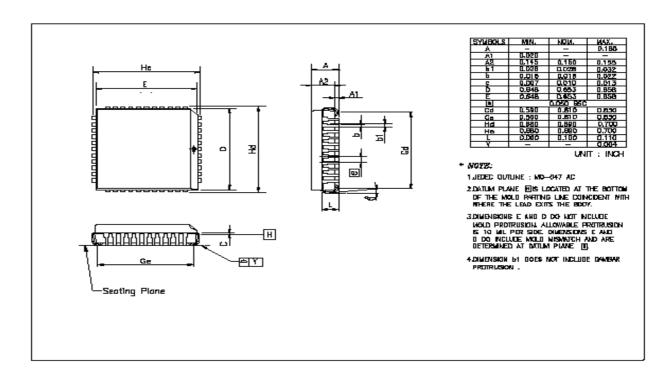
Symbol	Parameter	Test Condition	Specification			Unit
		rest Condition	Min.	Тур.	Max.	Ollit
Icc	Operating Current @20MHz	Vcc=3.3V	-	-	12	mA
lidle	Idle Mode Current @ 20MHz	Vcc=3.3V	-	-	6	mA
lpd	Power Down Current	Vcc=3.3V	-	-	50	uA
$V_{IL}$	Input High Voltage (P0, P1, P2, P3, P4, - EA)		0.8	-	-	V
V <sub>IH1</sub>	Input High Voltage (P0, P1, P2, P3, P4, - EA)	3.0V < Vcc < 3.6V	-	-	2.0	V
$V_{IH2}$	Input High Voltage (XTAL1, RST)	3.0V < Vcc < 3.6V	-	-	2.2	V
I <sub>OL1</sub>	Output Low Voltage (P1, P2, P3, P4)	Vcc=3.3V, Vpin=0.45V	-	6	-	mA
I <sub>OL2</sub>	Output Low Voltage (P0, ALE, PSEN)	Vcc=3.3V, Vpin=0.45V	-	12	-	mA
I <sub>OH1</sub>	Output High Voltage (P1, P2, P3, P4)	Vcc=3.3V, Vpin=2.4V	-	250	-	uA
I <sub>OH2</sub>	Output High Voltage (P0, ALE, PSEN)	Vcc=3.3V, Vpin=2.4V	-	12	-	mA
I <sub>LK</sub>	Input Leakage Current (P0, - EA)		1	-	10	uA
R <sub>RST</sub>	Internal Reset Pull-down Resistance	Vcc=3.3V	-	100	-	ΚΩ

### **Package Dimensions**

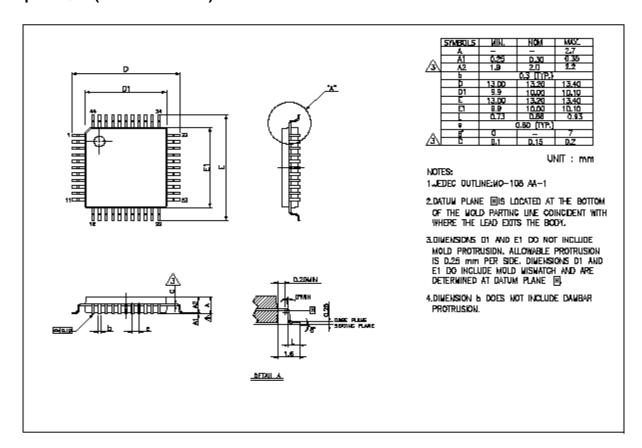
## 40-pin DIP (MPC89L516X2)



## 44-pin PLCC (MPC89L516X2P)



### 44-pin PQFP (MPC89L516X2F)



# **Version History**

Version	Date	Page	Description
A1	2003/10		Initial issue